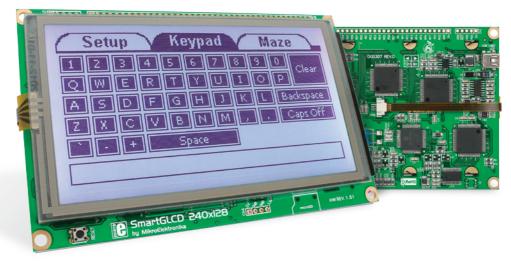
SmartGLCD 240x128







TO OUR VALUED CUSTOMERS

I want to express my thanks to you for being interested in our products and for having confidence in MikroElektronika.

The primary aim of our company is to design and produce high quality electronic products and to constantly improve the performance thereof in order to better suit your needs.

Nebojsa Matic General Manager

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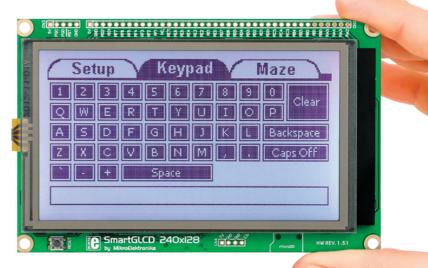
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What is the SmartGLCD 240x128?

The SmartGLCD 240x128 is a compact smart display, with many on-board peripherals. It's designed to become a control interface of your device. Main part of the board is a large 240x128 pixel graphical LCD with a 4-wire resistive touch screen. It features RGB backlight, which can greatly improve user experience, but can also be used as a signaling feature. The heart of the board is PIC18F87K22, an 8-bit microcontroller delivering 12MIPS of processing power. Other modules like USB UART, piezo buzzer, microSD slot and connection pads can be found on board as well. The board is preprogrammed with UART bootloader. We have also provided a nice example which will give you a great out-of-thebox experience.





Package Contains



1. Key Features

01 GLCD 240x128 display

2 RESET button



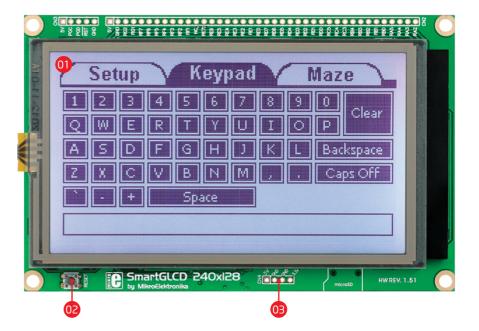
- Power supply pads
- 04 I/O pads
- 05 Pads for mikroProg programmer
- 06 USB connector

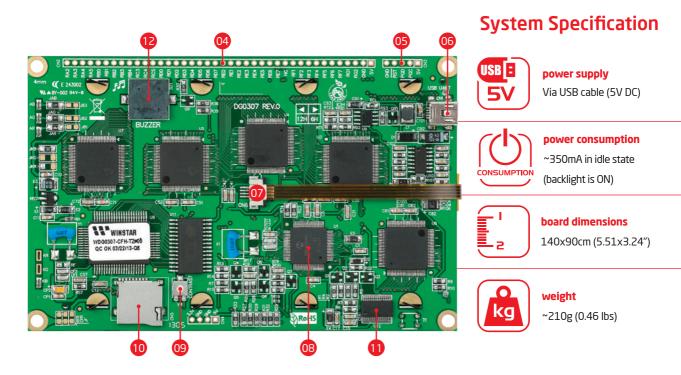


- Touch panel connector
- 08 PIC18F87K22 microcontroler
- 9 Contrast potentiometer
- 10 microSD card slot



12 Buzzer

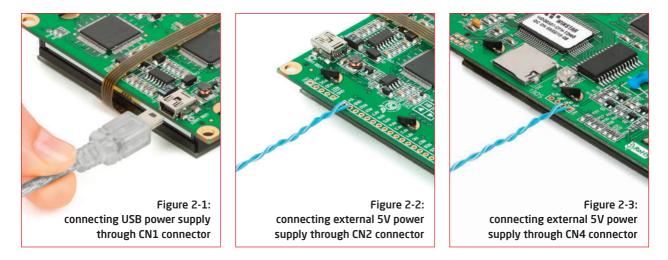




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2. Power supply

The SmartGLCD board can be powered in two different ways: via USB connector **(CN1)** using MINI-B USB cable provided with the board **(Figure 2-1)**, or via side headers **(CN2** or **CN4)** using external 5V power supply (**Figure 2-2** and **Figure 2-3**).



When the board is powered up the GLCD display will be automatically turned on. The USB connection can provide up to 500mA of current which is more than enough for the operation of all on-board modules and the microcontroller as well.

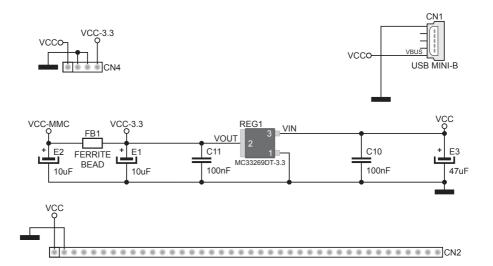


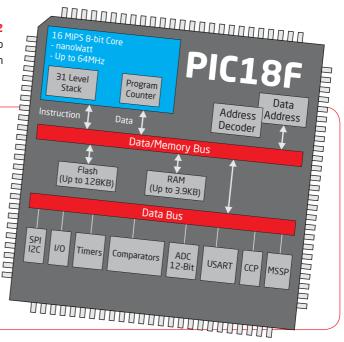
Figure 2-4: Power supply schematic

3. PIC18F87K22 microcontroller

The SmartGLCD development tool comes with the **PIC18F87K22** microcontroller. This 8-bit microcontroller is rich with on-chip peripherals and features 128KB of Flash and 4KB of RAM. It can easily handle demanding graphical applications.

Key microcontroller features

- Up to 12 MIPS Operation;
- 8-bit architecture;
- 128KB of Flash memory;
- 3,862 bytes of RAM;
- 1024 bytes of EEPROM;
- 80 pin TQFP;
- 24 ch, 12-bit ADC;
- UART, SPI, I²C; etc.



4. Programming the microcontroller



Figure 4-1: PIC18F87K22 microcontroller

The microcontroller can be programmed in two ways:



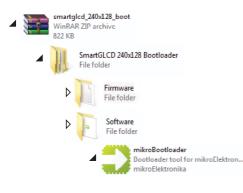
02 Using external mikroProgTM for PIC, dsPIC, PIC32 programmer

5. Programming with bootloader

Microcontroller is preprogrammed with USB UART Bootloader, which can be used to upload new device firmware. To transfer firmware .HEX file from a PC to MCU you need to use mikro-Bootloader USB UART application, which can be downloaded from:



Upon download, unzip it to desired location and start the mikroBootloader application:



mikroBootloader software

-	-	F	ч	-	

e Before starting mikroBootloader software, connect SmartGLCD to a PC using a USB cable provided with the package.

mikroElektronika Bootloader v2.1.0.0	X
mikroBootloader select MCC	J PIC18 -
1 Setup COM Port: COM1 Change Daud Rate: 19200 Settings	Conn Rx Tx
2 Connect Connect Ilistory Wind Setup: Port COM	
3 Choose Browse tor HEX	
4 Start Begin uploading	-
Bootloading progress bar	Show Activity
: No files opened.	

Figure 5-1: mikroBootloader window



When you start mikroBootloader software a window should appear, as shown in the image above.

Identifying device COM port

step 1 - Choosing COM port

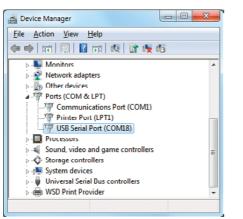


Figure 5-2: Identifying COM port



mikroElektronika Bootloader v2.1.0.0	Select MLU PIC18
port Daud Rate: 19200	Change 01 Conn Rx Tx Settings 02 Port COM 18 • Baud rate 115200 • Data bits 8 • Stop bits 1 • Panly None •
Bootloading progress bar	How control Goftware

Figure 5-3: Choosing COM port



Click the **Change Settings** button.

From the drop down list, select appropriate **Port** (in this case it is COM18) and **Baud rate** (115200).

```
Click OK.
```

step 2 - Establishing Connection

	t: COM18 te: 115200	Change Settings	-	onn Rx	Tx O
2 Connect	Connect	01 tup: Port COM1. Setup: Port COM18			~
HEX file	for HEX Begin uploading				-

Figure 5-4: Connecting with mikroBootloader



step 3 - Browsing for .HEX file

Secop	Port: COM18 d Rate: 115200	Change Settings	Signals	Conn	Rx O	Tx O
2 Connect to MCU	Disconnect	History Wi Setup: Port CO	M1.			
3 Choose HEX file	Browse for HEX	Setup: Port CO Waiting MCU re				
4 Start bootloader	Begin uploading					

Figure 5-5: Browse for HEX



Click the **Browse for HEX** button and from a pop-up window (Figure 5-6) choose a .HEX file to be uploaded in MCU memory.

step 4 - Selecting .hex file

Organize 👻 New fo	lder				· · ·	
Favorites	Name	Dat	e modified	Туре	Size	
E Desktop	SmartGLCD	.hex 🔴 28.3	2013 16:20	HEX File		16 KB
Secent Places						
 Libraries Documents Music Pictures Videos 		01				
Documents Music Pictures Videos						
Documents Music Fictures Videos Homegroup		U				
Documents Music Pictures		U				

Figure 5-6: Locating and selecting .hex file



Select .HEX file from the **Open dialog** window.

Click the **Open** button.

step 5 - Uploading .hex file

Secop	M Port: COM18 ud Rate: 115200	Change Settings	slanals Coun	Rx Tx
2 Connect	Disconnect	History Win	dow	
3 Choose HEX file	Browse for HEX	Setup: Port CON Waiting MCU res Connected. Opened: C:\Pro		nex
4 Start bootloade	Begin uploading	-01		

Figure 5-7: Begin uploading



In order to upload .HEX file click the **Begin** uploading button.

step 6 - Progress bar

	COM Port: COM18 Baud Rate: 115200	Change Settings	Signals Coun	Rx Tx
2 Connect	Disconnect	History Win	dow	
3 Choose HEX file		Setup: Port CON Setup: Port CON Waiting MCU res Connected. Opened: C: \Pro Uploading	418.	ex .
4 Start	der uploading			

Figure 5-8: Progress bar



Progress bar enables you to monitor .HEX file uploading.

step 7 - Finishing upload

Setup port	uccess	-	
Connec to MCU	Reset MCU. Uploading program	n has finished.	0
Choose HEX file	Show details		• ок
Start bootload	Begin (er uploading	Completed successfully.	

Figure 5-9: Restarting MCU

OI Click **OK** button after the uploading process has been finished.

02 Press Reset button on SmartGLCD board and wait for 5 seconds. Your program will run automatically.

Tips and Tricks: Speed-up UART data transfer

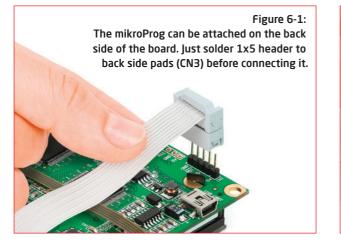
Device Manager	USB Serial Port (COM18) Properties	Advanced Settings for COM18
File Action View Help Image: State of the state of	General Pot Settings Driver. Details	COM Bort Number: COM18
- M Mice and other pointing devices Monitors - Network adapters - D Other devices	02 Deta bits: 8 ▼ Party: None ▼ Stop bits: 1 ▼	Select lower settings to correct performance problems at low baud rates. Select higher settings for faster performance. Receive (Bytes):
Ports (COM & LPT) Communications Port (COM1) Printer Port (LPT1) Update Driver Software S Disable	Bow control: Nane	Transmit (Bytes): 9096 • BM Options 004 Miscella Select lower settings to correct response problem. Serial B Serial P Latency Timer (msec): 100 • Cencel
Scan for hard Changes	OK Cencel	Timcouts Set RTS Minimum Read Timeout (msec): 0 v Minimum Write Timeout (msec): 0 v
Opens propert	UN Lancel	

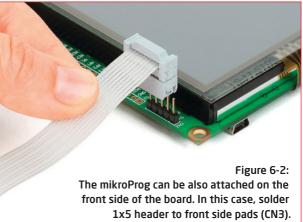
note If .HEX file transfer from your PC to MCU is too slow, it's possible to speed up data transfer by setting latency time of COM port to 1 ms. This is done in Device Manager:

- 01 02 04
 - Right click on the USB Serial Port (COM18) item and then select Properties.
 - Select Port Settings tab.
 - Click the **Advanced...** button.
 - Set Latency Timer to 1 and click OK.

6. Programming with mikroProg[™] programmer

The microcontroller can be programmed with the external **mikroProg**[™] programmer which can be connected to the board via **CN3** connector. Before establishing this connection it is necessary to solder 1x5 male header to **CN3** connection pads. This can be done in both ways: on the bottom, or the top side, as shown in **Figures 6-1** and **6-2**.





note If bootloader program is accidently erased you can upload it again through mikroProg programmer. Program Bootloader18F87K22.hex can be found under Firmware folder (page 12).

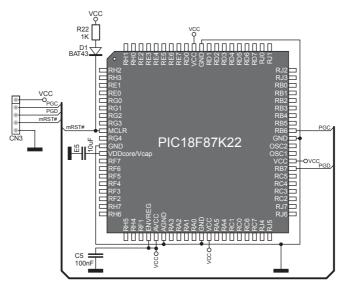


Figure 6-3: mikroProg[™] connection schematic



Make sure to use only the front row of mikroProg's IDC10 connector (side with a knob and incision) when connecting it to 1x5 header on your SmartGLCD board.



7. mikroProg Suite[™] for PIC[®] Software



The **mikroProg**^{TD} programmer requires special programming software called mikroProg Suite^{TT} for PIC[®]. It can be used for programming all Microchip® microcontroller families, including PIC10[®], PIC12°, PIC16°, PIC18°, dsPIC30/33°, PIC24[®] and PIC32[®]. The software has intuitive interface and SingleClick[™] programming technology. Just download the latest version of mikroProg Suite^T and your programmer is ready to program new devices. mikroProg **Suite**Th is updated regularly, at least four times a year, so your programmer will be more and more powerful with each new release



Figure 7-1: Main window of mikroProg Suite[™] for PIC[®] programming software

Software Installation Wizard

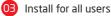




InvitorProg Suite For FIC Cancel











Finish installation



ers'Public'/Documents'/Microelektronika'/microProg Suite For PIC

Browse...

Cancel

< Back Instal

Dectination Folder

Space required: 37.3MB Space available: 23.1GB

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8. microSD Card Slot

Figure 8-1: microSD card slot

There is a built-in microSD card slot provided on-board. It enables the expansion of available memory space using microSD cards. Communication between the microcontroller and the card is done through Serial Peripheral Interface (**SPI**).

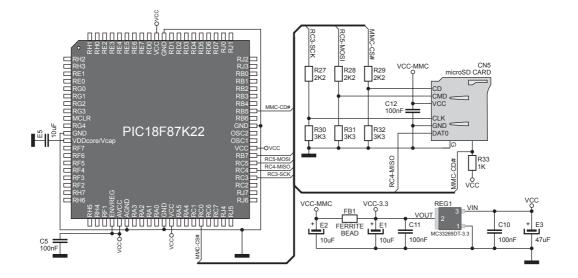
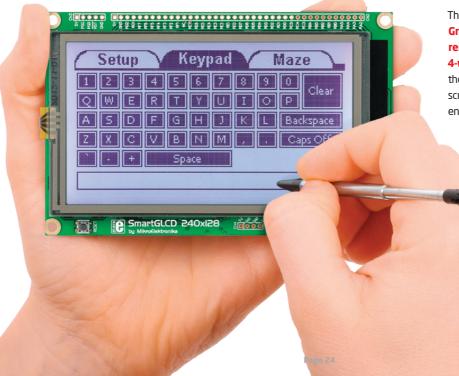


Figure 8-2: microSD Card Slot module connection schematic

9. Touch Screen



The development system features a **Graphical LCD in 240x128 pixel resolution**. Display is covered with a **4-wire resistive** touch panel. Together they form a functional unit called a touch screen, **Figure 9-1**. It enables data to be entered and displayed at the same time.

Figure 9-1: Touch Screen

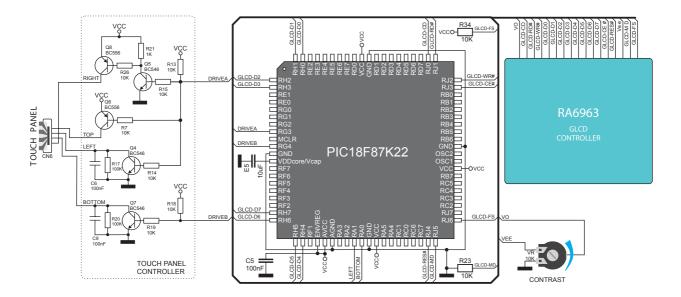
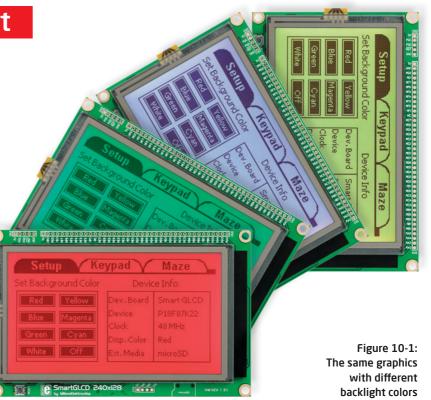


Figure 9-2: Touch Screen connection schematic

10. RGB backlight

Graphical LCDs are only capable of showing monochromatic pixel but not color content. The color of the pixel is determined by the color of the backlight which illuminates the display. SmartGLCD has **the RGB color backlight** - a very useful feature which can give your graphical user interfaces an astonishing look.

Display's backlight module consists of three LEDs: red, green and blue, which can shine simoutaneously. LED can be driven by PWM signals coming from three separate microcontroller pins. Duty ratio of the PWM signal determines the intensity of color (or brightness) of each LED. Combined together they can create more than 16 milion different backlight colors.



11. Contrast potentiometer

On the backside of the board there is a small potentiometer which can be used to change Figure 11-1: contrast of the GLCD. The brighter the backlight, the Constrast less contrast you will need to properly display the potentiometer graphical content.

12. USB UART

Figure 12-1: Connecting USB cable to SmartGLCD board



Fast on-board **FTDI*** **chip** allows you to communicate with a PC or other UART devices using USB UART connection. Before connecting the board to a PC, make sure that you have the appropriate **FTDI drivers** installed on your operating system. Drivers can be found on the **Product DVD**:

DVD://download/eng/software/development-tools/universal/ftdi/vcp_drivers.zip

USB-B connector (**CN1**) is used for connecting the USB cable, which is delivered with the board package. Plug it in as shown in **Figure 12-1**.

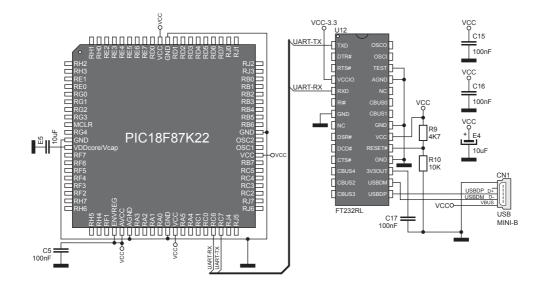


Figure 12-2: USB UART module connection schematic



Figure 13-1: Buzzer module

BUZZER

The board is also equipped with piezo buzzer. It is an electric component which can be used to create sound when provided with electrical signal. This is usually a PWM signal coming from a microcontroller pin. Before entering the buzzer itself, the signal is amplified by the on-board buzzer driver circuit. Frequency of the signal determines the pitch of the sound and duty cycle of the signal can be used to increase or decrease the volume.

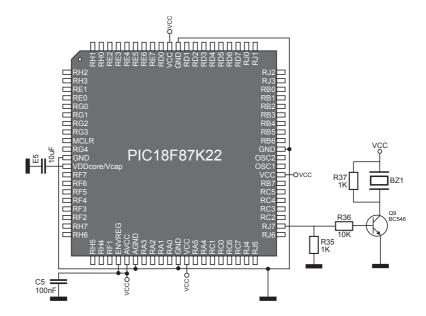
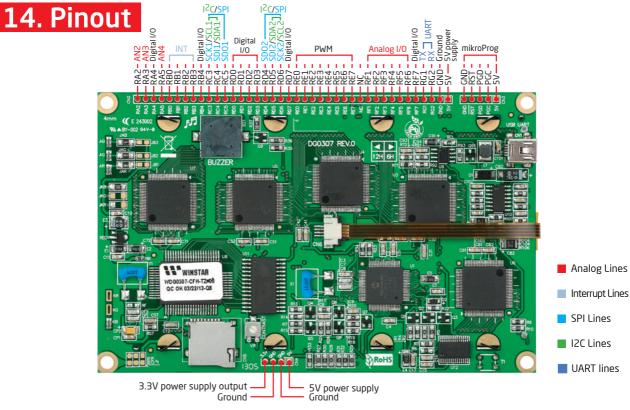


Figure 13-2: Buzzer module schematic



15. Dimensions

Legend

mm

Mounting hole size Ø 4 mm

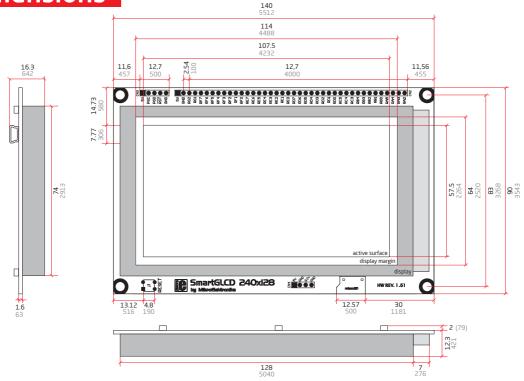
Tolerance +/- 0.5mm

mils

Pad hole size

Ø 1.14 mm Ø 45 mils

ø 157 mils



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o you can begin building your first applications.

Compiler

SOFTWARE

You still don't have an appropriate compiler? Locate PIC[®] compiler that suits you best on the Product DVD provided with the package:

DVD://download/eng/software/compilers/

Choose between mikroC[™], mikroBasic[™] and mikroPascal[™] and download fully functional demo version, so you can begin building your first applications.

Once you have chosen your compiler, and since you already got the board, you are ready to start writing your first projects. **Visual GLCD software** for rapid development of graphical user interfaces enables you to quickly create your GUI. It will automatically create necessary code which is compatible with mikroElektronika compilers. Visual GLCD is rich with examples, which are an excellent starting point for your future projects. Just load the example, read well commented code, and see how it works on hardware. Visual GLCD is also available on the Product DVD.

mikroC

COMPILER

PRO for PIC

roBASIC

COMPILER

oPASC/

COMPILER

PIC

What's next?

Your journey through each and every feature of SmartGLCD board ends here. You got to know it's modules and organization. Now you are ready to use it. We are suggesting several steps which are probably the best way to begin with. We invite you to join the users of SmartGLCD brand. You will find very useful projects and tutorials and can get help from a large ecosystem of users. Welcome!

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