EasyPIC Fusion v7

65 microcontrollers supported
PIC24®, dsPIC33® and pic32®

Many on-board modules
Multimedia peripherals

Easy-add extra boards
mikroBUS™ sockets

Two connectors for each port
Amazing Connectivity

Fast USB 2.0 programmer and
In-Circuit Debugger
Providing our users the ability to easily switch between architectures on the same development board has always been an engineering challenge for us. But we have mastered this technology during the past decade and now we present you the revolutionary board that combines support for three different microcontroller families: Microchip’s dsPIC33®, PIC24® and PIC32®. EasyPIC Fusion™ v7 is the ultimate board for all of your 16-bit and 32-bit PIC projects.

You made the right choice.

Nebojsa Matic,
Owner and General Manager
of MikroElektronika
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Introduction

EasyPIC Fusion™ v7 is the first board of its kind to combine support for three popular Microchip® low-power microcontroller architectures in one place. We wanted to put as many peripherals on the board as possible, to cover many internal modules. We have gone through a process of fine tuning the board performance, and used 4-layer PCB to achieve maximum efficiency. Finally, it had met all of our expectations, and even exceeded in some. We present you the board which is powerful, well organized, with on-board programmer and debugger and is ready to be your strong ally in development.

EasyPIC Fusion™ v7 development Team

One board for three architectures
dsPIC33, PIC24 & PIC32

For the first time we combined the power of three separate boards in one ultimate board for high performance Microchip MCUs. Developers now have the new scalability like never before.

Everything is already here
mikroProg™ on board

Powerful on-board mikroProg™ programmer and In-Circuit debugger supports over 65 microcontrollers. It features fast enhanced programming and rich set of debugging instructions.

Ready for all kinds of development
Multimedia peripherals

TFT 320x240 with touch panel, stereo mp3 codec, audio input and output, navigation switch and microSD card slot make a perfect set of peripherals for multimedia development.

For easier connections
mikroBUS™ support

This innovative new socket allows you to use dozens of Click accessory boards with almost no hardware adjustments. Adding new functionality to your device was never so easy.
It’s good to know

System Specifications

- **Power Supply**: 7-12V AC or 9-15V DC, or via USB cable (5V DC)
- **Power Consumption**: ~143mA (all modules are disconnected)
- **Board Dimensions**: 266 x 220mm (10.47 x 8.66 inch)
- **Weight**: ~460g (1.014 lbs)

Package contains

1. Damage resistant protective box
2. EasyPIC Fusion™ v7 board in antistatic bag
3. USB cable
5. Board schematic
6. mikroICD™ and mikroProg Suite™ manual
Power supply

Board contains switching power supply that creates stable voltage and current levels necessary for powering each part of the board. Power supply section contains specialized **MC33269DT3.3** power regulator which creates VCC-3.3V power supply, thus making the board capable of supporting 3.3V microcontrollers. Power supply unit can be powered in three different ways: with **USB power supply (CN20)**, using external adapters via adapter connector (CN30) or additional screw terminals (CN31). External adapter voltage levels must be in range of **9-15V DC and 7-12V AC**. Use jumper J9 to specify which power source you are using. Upon providing the power using either external adapters or USB power source you can turn on power supply by using **SWITCH 1 (Figure 3-1)**. Power **LED ON (Green)** indicates the presence of power supply.

Figure 3-2: Power supply unit schematic

![Power supply schematic](image)
How to power the board?

1. With USB cable

   Set J9 jumper to USB position

   To power the board with USB cable, place jumper J9 in USB position. You can then plug in the USB cable as shown on images 1 and 2, and turn the power switch ON.

2. Using adapter

   Set J9 jumper to EXT position

   To power the board via adapter connector, place jumper J9 in EXT position. You can then plug in the adapter cable as shown on images 3 and 4, and turn the power switch ON.

3. With laboratory power supply

   Set J9 jumper to EXT position

   To power the board using screw terminals, place jumper J9 in EXT position. You can then screw-on the cables in the screw terminals as shown on images 5 and 6, and turn the power switch ON.

Board power supply creates stable 3.3V necessary for operation of the microcontroller and all on-board modules.

Power supply: via DC connector or screw terminals (7V to 12V AC or 9V to 15V DC), or via USB cable (5V DC)

Power capacity: up to 500mA with USB, and up to 1500mA with external power supply
MCU cards

Microcontrollers are supported using specialized MCU cards containing 104 pins, which are placed into the on-board female MCU socket. There are several types of cards which cover PIC24x, dsPIC33x, PIC32MX4xx, PIC32MX7xx microcontroller families in 100-pin TQFP packages. One of the MCU cards is shown on Figure 4-1. It contains PIC32MX795F512L microcontroller with on-chip peripherals and is a great choice for both beginners and professionals. After testing and building the final program, this card can also be taken out of the board socket and used in your final device.

**Figure 4-1: MCU card with PIC32MX795F512L**

1. PIC32MX795F512L has **80MHz maximum frequency**, **512K bytes** of program memory (flash), **128K bytes** of data memory. It has integrated Ethernet controller, USB (OTG, Host, Device), 85 General purpose I/O pins, 5 16-bit timers, 16 Analog Input pins (ADC), 6 UARTs, internal 8 MHz and 32kHz oscillators, internal Real time clock (RTC), 5 I2C, 4 SPI and 2 CAN controllers. It also contains 3 analog comparators and two programming and debugging interfaces.

2. **8MHz crystal oscillator.** We carefully chose the most convenient crystal value that provides clock frequency which can be used directly, or with the PLL multipliers to create higher MCU clock value. MCU card also contains 32.768 kHz crystal oscillator which provides external clock waveform for RTCC module.

3. **USB communications lines.** These two jumpers, when in USB position, connect D+ and D- lines of the on-board USB connector with RG2 and RG3 microcontroller pins. Since PIC32MX795F512L supports USB, jumpers are in USB position.

4. **Ethernet transceiver.** This MCU card contains single-chip Ethernet physical (PHY) layer transceiver which provides additional Ethernet functionality to PIC32MX795F512L controller.

5. **25MHz crystal oscillator.** This crystal oscillator is connected to external Ethernet module.
Figure 4-2: ETHERNET MCU card schematic
How to properly place your MCU card into the socket?

Before you plug the microcontroller card into the socket, make sure that the **power supply is turned off**. Images below show how to correctly plug the MCU card. First make sure that MCU card orientation matches the silkscreen outline on the EasyPIC Fusion™ v7 board MCU socket. Place the MCU card over the socket so each male header is properly aligned with the female socket as shown in **Figure 4-4**. Then put the MCU card slowly down until all the pins match the socket. Check again if everything is placed correctly and press the MCU card until it is completely plugged into the socket as shown in **Figure 4-5**. If done correctly all pins should be fully inserted. Only now you can turn on the power supply.

1. **Figure 4-3**: On-board MCU socket has silkscreen markings which will help you to correctly orient the MCU card before inserting.

2. **Figure 4-4**: Place the MCU card on the socket so that pins are aligned correctly.

3. **Figure 4-5 Properly placed MCU card.**
Other supported MCU cards

MikroElektronika currently offers a total of five populated MCU cards with different microcontrollers. You can also purchase empty PCB cards that you can populate on your own and solder any supported microcontroller you need in your development. There are a total of five empty PCB cards available. This way your EasyPIC Fusion™ v7 board becomes truly flexible and reliable tool for almost any of your PIC24®, dsPIC33® and PIC32® projects. MCU cards can also be used in your final devices. For complete list of currently available MCU cards, please visit the board webpage:

www.mikroe.com/easypic-fusion/
On-board programmer

What is mikroProg™?

mikroProg™ is a fast USB 2.0 programmer with mikroICD™ hardware In-Circuit Debugger. Smart engineering allows mikroProg™ to support all PIC10, PIC12, PIC16, PIC18, PIC24, dsPIC30/33, PIC32 MCU families in a single programmer! It supports over 570 microcontrollers from Microchip®. Outstanding performance and easy operation are among its top features.

How do I start?

In order to start using mikroProg™ and program your microcontroller, you just have to follow two simple steps:

1. **Install the necessary software**
   - Install USB drivers (Page 14)
   - Install mikroProg Suite™ for PIC® software (Page 15)

2. **Power up the board, and you are ready to go.**
   - Plug in the programmer USB cable
   - Turn on Power switch
   - LINK and POWER LED should light up.

Why so many LEDs?

Three LEDs indicate specific programmer operation, Figure 5-1. **Link** LED lights up when USB link is established with your PC. **Active** LED lights up when programmer is active. **Data** LED lights up when data is being transferred between the programmer and PC software (compiler or mikroProg Suite™ for PIC®).

Programming with ICD2/ICD3

EasyPIC Fusion™ v7 is equipped with RJ-12 connector compatible with Microchip® ICD2® and ICD3® external programmers. You can either use the on-board mikroProg™ programmer or external programming tools as long as you use only one of them at the same time. Insert your ICD programmer cable into connector **CN33**, as shown in images ① and ②.
Figure 5-2: mikroProg™ block schematic
Installing programmer drivers

On-board mikroProg™ requires drivers in order to work. Drivers can be found on the link below:


When you locate the drivers, please extract files from the ZIP archive. Folder with extracted files contains sub folders with drivers for different operating systems. Depending on which operating system you use, choose adequate folder and open it.

Step 1 - Start Installation
Welcome screen of the installation. Just click on Next button to proceed.

Step 2 - Accept EULA
Carefully read End User License Agreement. If you agree with it, click Next to proceed.

Step 3 - Installing drivers
Drivers are installed automatically in a matter of seconds.

Step 4 - Finish installation
You will be informed if the drivers are installed correctly. Click on Finish button to end installation process.
Programming software

mikroProg Suite™ for PIC®

On-board mikroProg™ programmer requires special programming software called mikroProg Suite™ for PIC®. This software is used for programming all of Microchip® microcontroller families, including PIC10, PIC12, PIC16, PIC18, dsPIC30/33, PIC24 and PIC32. Software has intuitive interface and SingleClick™ programming technology. To begin, first locate the installation archive on our website:


After downloading, extract the package and double click the executable setup file, to start installation.

Installation wizard - 6 simple steps

Step 1 - Start Installation

Step 2 - Accept EULA and continue

Step 3 - Install for All users or current user

Step 4 - Choose destination folder

Step 5 - Installation in progress

Step 6 - Finish Installation
mikroICD™ - In Circuit Debugger

What is Debugging?

Every developer comes to a point where he has to monitor the code execution in order to find errors in the code, or simply to see if everything is going as planned. This hunt for bugs or errors in the code is called debugging. There are two ways to do this: one is the software simulation, which enables you to simulate what is supposed to be happening on the microcontroller as your code lines are executed and the other, most reliable one, is monitoring the code execution on the MCU itself. And this latter one is called In-Circuit debugging. "In-Circuit" means that it is the real deal - code executes right on the target device.

What is mikroICD™?

The on-board mikroProg™ programmer supports mikroICD™ - a highly effective tool for a Real-Time debugging on hardware level. The mikroICD™ debugger enables you to execute your program on the host PIC microcontroller and view variable values, Special Function Registers (SFR), RAM, CODE and EEPROM memory along with the mikroICD™ code execution on hardware. Whether you are a beginner, or a professional, this powerful tool, with intuitive interface and convenient set of commands will enable you to track down bugs quickly. mikroICD™ is one of the fastest, and most reliable debugging tools on the market.

Supported Compilers

All MikroElektronika compilers, mikroC, mikroBasic and mikroPascal for PIC®, dsPIC® and PIC32® natively support mikroICD™. Specialized mikroICD DLL module allows compilers to exploit the full potential of fast hardware debugging. Along with compilers, make sure to install the appropriate programmer drivers and mikroProg Suite for PIC® programming software, as described on pages 14 and 15.

How do I use the debugger?

When you build your project for debugging, and program the microcontroller with this HEX file, you can start the debugger using [F9] command. Compiler will change layout to debugging view, and a blue line will mark where code execution is currently paused. Use debugging toolbar in the Watch Window to guide the program execution, and stop anytime. Add the desired variables to Watch and monitor their values. Complete guide to using mikroICD™ with your compiler is provided within the EasyPIC Fusion™ v7 package.
Here is a short overview of which debugging commands are supported in MikroElektronika compilers. You can see what each command does, and what are their shortcuts when you are in debugging mode. It will give you some general picture of what your debugger can do.

<table>
<thead>
<tr>
<th>Toolbar Icon</th>
<th>Command Name</th>
<th>Shortcut</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>![Icon]</td>
<td>Start Debugger</td>
<td>[F9]</td>
<td>Starts Debugger.</td>
</tr>
<tr>
<td>![Icon]</td>
<td>Run/Pause Debugger</td>
<td>[F6]</td>
<td>Run/Pause Debugger.</td>
</tr>
<tr>
<td>![Icon]</td>
<td>Stop Debugger</td>
<td>[Ctrl + F2]</td>
<td>Stops Debugger.</td>
</tr>
<tr>
<td>![Icon]</td>
<td>Step Into</td>
<td>[F7]</td>
<td>Executes the current program line, then halts. If the executed program line calls another routine, the debugger steps into the routine and halts after executing the first instruction within it.</td>
</tr>
<tr>
<td>![Icon]</td>
<td>Step Over</td>
<td>[F8]</td>
<td>Executes the current program line, then halts. If the executed program line calls another routine, the debugger will not step into it. The whole routine will be executed and the debugger halts at the first instruction following the call.</td>
</tr>
<tr>
<td>![Icon]</td>
<td>Step Out</td>
<td>[Ctrl + F8]</td>
<td>Executes all remaining program lines within the subroutine. The debugger halts immediately upon exiting the subroutine.</td>
</tr>
<tr>
<td>![Icon]</td>
<td>Run To Cursor</td>
<td>[F4]</td>
<td>Executes the program until reaching the cursor position.</td>
</tr>
<tr>
<td>![Icon]</td>
<td>Toggle Breakpoint</td>
<td>[F5]</td>
<td>Toggle breakpoints option sets new breakpoints or removes those already set at the current cursor position.</td>
</tr>
<tr>
<td>![Icon]</td>
<td>Show/Hide breakpoints</td>
<td>[Shift+F4]</td>
<td>Shows/Hides window with all breakpoints</td>
</tr>
<tr>
<td>![Icon]</td>
<td>Clears breakpoints</td>
<td>[Shift+Ctrl+F5]</td>
<td>Delete selected breakpoints</td>
</tr>
<tr>
<td>![Icon]</td>
<td>Jump to interrupt</td>
<td>[F2]</td>
<td>Opens window with available interrupts (doesn’t work in mikroICD™ mode)</td>
</tr>
</tbody>
</table>
One of the most distinctive features of EasyPIC Fusion™ v7 are its Input/Output PORT groups. They add so much to the connectivity potential of the board.

Everything is grouped together

PORT headers, PORT buttons and PORT LEDs next to each other and grouped together. It makes development easier, and the entire EasyPIC Fusion™ v7 cleaner and well organized. We have also provided an additional PORT headers on the right side of the board, so you can access any pin you want from that side of the board too.

Tri-state pull-up/down DIP switches

Tri-state DIP switches, like Sw7 on Figure 6-3, are used to enable 4K7 pull-up or pull-down resistor on any desired port pin. Each of these switches has three states:
1. middle position disables both pull-up and pull-down feature from the PORT pin
2. up position connects the resistor in pull-up state to the selected pin
3. down position connects the resistor in pull-down state to the selected PORT pin.

Button press level tri-state DIP switch is used to determine which logic level will be applied to port pins when buttons are pressed.
Headers

With enhanced connectivity as one of the key features of EasyPIC Fusion™ v7, we have provided two connection headers for each PORT. I/O PORT group contains one male IDC10 header (like CN13 Figure 6-3). There is one more IDC10 header available on the right side of the board, next to DIP switches (like CN16 on Figure 6-3). These headers can be used to connect accessory boards with IDC10 female sockets.

Buttons

The logic state of all microcontroller digital inputs may be changed using push buttons. Tri-state DIP switch SW10 is available for selecting which logic state will be applied to corresponding MCU pin when button is pressed, for each I/O port separately. If you, for example, place Sw10.6 in VCC position, then pressing of any push button in PORTF I/O group will apply logic one to the appropriate microcontroller pin. The same goes for GND. If DIP switch is in the middle position neither of two logic states will be applied to the appropriate microcontroller pin. You can disable pin protection 220ohm resistors by placing jumpers J6 and J7, which will connect your push buttons directly to VCC or GND. Be aware that doing so you may accidentally damage MCU in case of wrong usage.

Figure 6-5: Button press level DIP switch (tri-state)

LEDs

LED (Light-Emitting Diode) is a highly efficient electronic light source. When connecting LEDs, it is necessary to place a current limiting resistor in series so that LEDs are provided with the current value specified by the manufacturer. The current varies from 0.2mA to 20mA, depending on the type of the LED and the manufacturer. The EasyPIC Fusion™ v7 board uses low-current LEDs with typical current consumption of 0.2mA or 0.3mA. Board contains 68 LEDs which can be used for visual indication of the logic state on PORT pins. An active LED indicates that a logic high (1) is present on the pin. In order to enable PORT LEDs, it is necessary to enable the corresponding DIP switch on Sw15 (Figure 6-6).

Figure 6-6: SW15.1 through Sw15.8 switches are used to enable PORT LEDs

Reset Button

In the far upper right section of the board, there is a RESET button, which can be used to manually reset the microcontroller.

Figure 6-4: IDC10 male headers enable easy connection with MikroElektronika accessory boards

Figure 6-3: I/O PORT group contains one male IDC10 header (like CN13). There is one more IDC10 header available on the right side of the board, next to DIP switches (like CN16 on Figure 6-3). These headers can be used to connect accessory boards with IDC10 female sockets.

Figure 6-5: Button press level DIP switch (tri-state)

Figure 6-6: SW15.1 through Sw15.8 switches are used to enable PORT LEDs

Figure 6-7: LED (Light-Emitting Diode) is a highly efficient electronic light source. When connecting LEDs, it is necessary to place a current limiting resistor in series so that LEDs are provided with the current value specified by the manufacturer. The current varies from 0.2mA to 20mA, depending on the type of the LED and the manufacturer. The EasyPIC Fusion™ v7 board uses low-current LEDs with typical current consumption of 0.2mA or 0.3mA. Board contains 68 LEDs which can be used for visual indication of the logic state on PORT pins. An active LED indicates that a logic high (1) is present on the pin. In order to enable PORT LEDs, it is necessary to enable the corresponding DIP switch on Sw15 (Figure 6-6).

Figure 6-8: RESET button, which can be used to manually reset the microcontroller.

EasyPIC Fusion™ v7

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mikroBUS™ sockets

Easier connectivity and simple configuration are imperative in modern electronic devices. Success of the USB standard comes from its simplicity of usage and high and reliable data transfer rates. As we in MikroElektronika see it, Plug-and-Play devices with minimum settings are the future in embedded world too. This is why our engineers have come up with a simple, but brilliant pinout with lines that most of today’s accessory boards require, which almost completely eliminates the need of additional hardware settings. We called this new standard the mikroBUS™. EasyPIC Fusion™ v7 supports mikroBUS™ with two on-board sockets. As you can see, there are no additional DIP switches, or jumper selections. Everything is already routed to the most appropriate pins of the microcontroller sockets.

mikroBUS™ host connector

Each mikroBUS™ host connector consists of two 1x8 female headers containing pins that are most likely to be used in the target accessory board. There are three groups of communication pins: SPI, UART and I2C communication. There are also single pins for PWM, Interrupt, Analog Input, Reset and Chip Select. Pinout contains two power groups: +5V and GND on one header and +3.3V and GND on the other 1x8 header.

Integrate mikroBUS™ in your design

mikroBUS™ is not made to be only a part of our development boards. You can freely place mikroBUS™ host connectors in your final PCB designs, as long as you clearly mark them with mikroBUS™ logo and footprint specifications. For more information, logo artwork and PCB files visit our web site:

http://www.mikroe.com/mikrobus/
MikroElektronika portfolio of over 200 accessory boards is now enriched by an additional set of mikroBUS™ compatible Click Boards™. Almost each month several new Click boards™ are released. It is our intention to provide the community with as much of these boards as possible, so you will be able to expand your EasyPIC Fusion™ v7 with additional functionality with literally zero hardware configuration. Just plug and play. Visit the Click boards™ web page for the complete list of available boards:

http://www.mikroe.com/click/

Click Boards™ are plug-n-play!
USB-UART A

The UART (universal asynchronous receiver/transmitter) is one of the most common ways of exchanging data between the MCU and peripheral components. It is a serial protocol with separate transmit and receive lines, and can be used for full-duplex communication. Both sides must be initialized with the same baud rate, otherwise the data will not be received correctly.

Modern PC computers, laptops and notebooks are no longer equipped with RS-232 connectors and UART controllers. They are nowadays replaced with USB connectors and USB controllers. Still, certain technology enables UART communication to be done via USB connection. Controllers such as FT232RL from FTDI convert UART signals to the appropriate USB standard.

USB-UART A communication is being done through a FT232RL controller, USB connector (CN22), and microcontroller UART module. To establish this connection, you must connect RX and TX lines of the FT232RL to the appropriate pins of the microcontroller. This selection is done using DIP switches SW12.1 and SW12.2.

In order to enable USB-UART A communication you must push SW12.1 and SW12.2 to ON position. This connects the RX and TX lines to RF5 and RF4 microcontroller pins.

In order to use USB-UART A module on EasyPIC Fusion™ v7, you must first install FTDI drivers on your computer. Drivers can be found on link below:

http://www.ftdichip.com/Drivers/VCP.htm

Figure 8-1: USB-UART A connection schematic
USB-UART B

Enabling USB-UART B

If you need to use more than one USB-UART in your application, you have another USB-UART B connector available on the board too. Both available USB-UART modules can operate at the same time, because they are routed to separate microcontroller pins.

USB-UART B communication is being done through a FT232RL controller, USB connector (CN23) and microcontroller UART module. To establish this connection, you must connect RX and TX lines of the FT232RL to the appropriate pins of the microcontroller. This selection is done using DIP switches SW12.3 and SW12.4 or SW12.5 and SW12.6.

When using either USB-UART A or USB-UART B, make sure to disconnect all devices and additional boards that could interfere with the signals and possibly corrupt the data being sent or received.

In order to enable USB-UART B communication, you must push SW12.3 and SW12.4 or SW12.5 and SW12.6 to ON position. This connects the RX and TX lines to appropriate microcontroller pins.

In order to use USB-UART B module on EasyPIC Fusion™ v7, you must first install FTDI drivers on your computer. Drivers can be found on link below:

http://www.ftdichip.com/Drivers/VCP.htm
USB HOST

USB is the acronym for Universal Serial Bus. This is a very popular industry standard that defines cables, connectors and protocols used for communication and power supply between computers and other devices. EasyPIC Fusion v7 contains USB HOST connector (CN24) for USB Standard Type A plug, which enables microcontrollers that support USB communication to establish a connection with the target device (e.g., USB Keyboard, USB Mouse, etc.). USB host also provides the necessary 5V power supply to the target via TPS2041B IC. Detection whether USB device is connected to HOST connector can be done through VBUS line. You can enable or disable USB device power supply connected to HOST via SW14.7 switch.

Figure 10-1: USB host connection schematic
EasyPIC Fusion™ v7 also contains USB DEVICE connector (CN26) which enables microcontrollers that support USB communication to establish a connection with the target host (e.g., PC, Laptop, etc.). It lets you build a slave USB device (HID, Composite, Generic, etc.). Connector supports USB Standard Type B plug. Detection whether USB device is connected to HOST can be done through VBUS line. This line is connected directly to microcontroller pin. When connected to HOST, dedicated amber-colored power LED will light up as well. This VCC line cannot be used for powering the board. It’s only used for detecting connection.

Figure 11-1: USB device connection schematic
Ethernet is a popular computer networking technology for local area networks (LAN). Systems communicating over Ethernet divide a stream of data into individual packets called frames. Each frame contains source and destination addresses and error-checking data so that damaged data can be detected and re-transmitted. EasyPIC Fusion™ v7 features standard RJ-45 connector which enables microcontrollers that support Ethernet communication to establish a connection with a computer, router or other devices. All four Ethernet lines (TPOUT+, TPOUT-, TPIN+ and TPIN-) are routed directly to the MCU card socket and cannot be accessed via PORT headers. Additional signalization LEDs (green and yellow) are provided on the board next to RJ-45 connector.

Figure 12-1: Ethernet connection schematic

Ethernet communication (TX_P, TX_N, RX_P and RX_N) and signalization lines (LED1, LED2) are routed directly to the MCU card socket and can be used only with an Ethernet MCU card (100-pin TQFP PT ETHERNET , Page 11).
Controller Area Network (CAN or CAN bus) is a vehicle bus standard designed to allow microcontrollers and devices to communicate with each other within a vehicle without a host computer. CAN is a message-based protocol, designed specifically for automotive applications but now also used in other areas such as industrial automation and medical equipment. EasyPIC Fusion™ v7 is equipped with SN65HVD230 - a 3.3V CAN Transceiver and a pair of screw terminals which provide microcontrollers with integrated CAN controller with the necessary physical interface for CAN communication. Make sure to correctly connect negative and positive differential communication lines before using this module.

In order to enable CAN communication, you must push SW12.7 (RG1) and SW12.8 (RG0) to ON position. This connects the TX and RX lines to appropriate microcontroller pins.
Audio I/O

It's hard to imagine modern multimedia devices without high quality audio reproduction modules. Sounds and music are almost as important as graphical user interfaces. Along with other multimedia modules, EasyPIC Fusion™ v7 contains high-end stereo VS1053 audio codec. It features Ogg Vorbis/MP3/AAC/wMA/FLAC/wAV/MIDI audio decoder, as well as an PCM/IMA ADPCM/Ogg Vorbis encoder on a single chip. Board also contains two stereo audio connectors for interfacing with standard 3.5mm stereo audio jacks. VS1053 receives the input bit stream through a serial input bus, which it listens to as a system slave. The input stream is decoded and passed through a digital volume control to an 18-bit oversampling, multi-bit, sigma-delta Digital to Analog Converter (DAC). The decoding is controlled via a serial control bus. In addition to the basic decoding, it is possible to add application specific features like DSP effects to the user RAM memory. You can build music players, audio recording devices, internet radio player applications, and much more.

Enabling Audio I/O

In order to use Audio I/O module, you must connect data and Audio control lines of the microcontroller with the VS1053 audio codec. To do this, push SW13.1-SW13.3 and SW13.5-SW13.8 switches to ON position. This will connect SPI data lines with SCK, MISO and MOSI microcontroller pins, and audio control lines and chip select with RG12, RG13, RG14 and RG15 pins.
Secure Digital (SD) is a non-volatile memory card format developed for use in portable devices. It comes in different packages and memory capacities. It is mostly used for storing large amounts of data. EasyPIC Fusion™ v7 features the microSD card slot. The microSD form factor is the smallest card format currently available. It uses standard SPI user interface with minimum additional electronics, mainly used for stabilizing communication lines which can be significantly distorted at high transfer rates. Special ferrite is also provided to compensate the voltage and current glitch that can occur when pushing-in and pushing-out microSD card into the socket.

Enabling microSD

In order to access microSD card, you must enable SPI communication lines using Sw13.1 - Sw13.3 DIP switches as well as Chip Select (CS) and Card Detect (CD) lines using Sw14.1 and Sw14.2 switches.

Figure 15-1: microSD card slot connection schematic
One of the most powerful ways of presenting data and interacting with users is through color displays and touch panel inputs. This is a crucial element of any multimedia device. EasyPIC Fusion™ v7 features TFT color 320x240 pixel display. It is a 2.83” display with LED back-light, featuring HX8347D controller. Each pixel is capable of showing 262,144 different colors. It is connected to microcontroller using standard 8080 parallel 8-bit interface, with additional control lines. Board features back-light driver which besides standard mode can also be driven with PWM signal in order to regulate brightness in range from 0 to 100%.

Enabling TFT display

TFT display is enabled using SW11.1-SW11.2 DIP switches. Back-light can be enabled in two different ways:

1. It can be turned on with full brightness using SW11.1 switch.
2. Brightness level can be determined with PWM signal from the microcontroller, allowing you to write custom back-light controlling software. This back-light mode is enabled when both SW11.1 and SW11.2 switches are in ON position.
Touch Panel controller

Touch panel is a glass panel whose surface is covered with two layers of resistive material. When the screen is pressed, the outer layer is pushed onto the inner layer and appropriate controllers can measure that pressure and pinpoint its location. This is how touch panels can be used as an input devices. EasyPIC Fusion™ v7 is equipped with touch panel controller and connector for 4-wire resistive touch panels. It can very accurately register pressure at a specific point, representing the touch coordinates in the form of analog voltages, which can then be easily converted to X and Y values. Touch panel comes as a part of TFT 320x240 display.

Enabling Touch panel

Touch panel is enabled using SW11.5, SW11.6, SW11.7 and SW11.8 switches. They connect TOP and LEFT lines of the touch panel with PB14 and RB15 analog inputs, and BOTTOM and RIGHT with PB2 and PB3 digital outputs on microcontroller sockets. Make sure to disconnect other peripherals, LEDs and additional pull-up or pull-down resistors from the interface lines so they do not interfere with signal/data integrity.

Figure 17-2: Turn on switches 5 through 8 on SW11 to enable Touch panel controller

Figure 17-1: Touch Panel controller and connection schematic
When working with multimedia applications it is far more intuitive to use a single joystick than several different push buttons that are more far apart. This is more natural for users and they can browse through on-screen menus, or even play games much easier. EasyPIC Fusion™ v7 features navigation switch with five different positions: **Up, Down, Left, Right** and **Center**. Each of those acts as a button, and is connected to one of the following microcontrollers pins: **RA4, RA5, RA6, RA7, RA1** (respectively). Before using the navigation switch, it is necessary to pull-up mentioned microcontroller pins using tri-state DIP switches located in I/O groups. After pressing the navigation switch in desired direction, associated microcontroller pins are connected to GND, which can be detected in user software.

![Navigation switch](image)

**Figure 18-1:** Navigation switch connection schematic. Pull-up resistors should be enabled during operation.

**Figure 18-2:** Navigation switch is an intuitive solution for browsing through on-screen menus.
Piezoelectricity is the charge which accumulates in certain solid materials in response to mechanical pressure, but also providing the charge to the piezo electric material causes it to physically deform. One of the most widely used applications of piezoelectricity is the production of sound generators, called piezo buzzers. Piezo buzzer is an electric component that comes in different shapes and sizes, which can be used to create sound waves when provided with analog electrical signal. EasyPIC Fusion™ v7 comes with piezo buzzer which can be connected to RD3 microcontroller pin. Connection is established using Sw14.8 DIP switch. Buzzer is driven by transistor Q1. Microcontrollers can create sound by generating a PWM (Pulse Width Modulated) signal - a square wave signal, which is nothing more than a sequence of logic zeros and ones. Frequency of the square signal determines the pitch of the generated sound, and duty cycle of the signal can be used to increase or decrease the volume in the range from 0% to 100% of the duty cycle. You can generate PWM signal using hardware capture-compare module, which is usually available in most microcontrollers, or by writing a custom software which emulates the desired signal waveform.

**Supported sound frequencies**

Piezo buzzer’s resonant frequency (where you can expect it’s best performance) is **3.8kHz**, but you can also use it to create sound in the range between **2kHz** and **4kHz**.

**How to make it sing?**

Buzzer starts “singing” when you provide PWM signal from the microcontroller to the buzzer driver. The pitch of the sound is determined by the frequency, and amplitude is determined by the duty cycle of the PWM signal.
DS1820 is a digital temperature sensor that uses **1-wire® interface** for its operation. It is capable of measuring temperatures within the range of -55 to 128°C, and provides ±0.5°C accuracy for temperatures within the range of -10 to 85°C. It requires 3V to 5.5V power supply for stable operation. It takes maximum of 750ms for the DS1820 to calculate temperature with 9-bit resolution. **1-wire® serial communication** enables data to be transferred over a single communication line, while the process itself is under the control of the master microcontroller. The advantage of such communication is that only one microcontroller pin is used. Multiple sensors can be connected on the same line. All slave devices by default have a unique ID code, which enables the master device to easily identify all devices sharing the same interface. Board provides a separate socket (**TS1**) for the DS1820. Communication line with the microcontroller is selected using **SW11.3** DIP switch (ON position).

EasyPIC Fusion™ v7 enables you to establish 1-wire® communication between **DS1820** and the microcontroller over **RA0** pin. The connection is done placing **Sw11.3** DIP switch to ON position (**Figure 20-4**). When placing the sensor in the socket make sure that half-circle on the board silkscreen markings matches the rounded part of the DS1820 sensor. If you accidentally connect the sensor the other way, it may be permanently damaged. Make sure to disconnect other peripherals, LEDs and additional pull-up or pull-down resistors from the interface lines in order not to interfere with signal/data integrity.
The **LM35** is a low-cost precision integrated-circuit temperature sensor, whose output voltage is linearly proportional to the Celsius (Centigrade) temperature. The LM35 thus has an advantage over linear temperature sensors calibrated in ° Kelvin, as the user is not required to subtract a large constant voltage from its output to obtain convenient Centigrade scaling. It has a linear +10.0 mV/°C scale factor and less than 60 μA current drain. As it draws only 60 μA from its supply, it has very low self-heating, less than 0.1°C in still air. EasyPIC Fusion™ v7 enables you to get analog readings from the LM35 sensor in restricted temperature range from +2°C to +150°C. Board provides a separate socket (TS2) for the LM35 sensor in TO-92 plastic packaging. Readings are done with microcontroller using single analog input line, which is selected with DIP switch SW11.4. Switch connects the sensor with RB0 microcontroller pin.

### Enabling LM35 Sensor

EasyPIC Fusion™ v7 enables you to get analog readings from the LM35 sensor using RB0 microcontroller pin. The selection of this line is done placing Sw11.4 DIP switch to ON position (Figure 21-4). When placing the sensor in the socket make sure that half-circle on the board silkscreen markings matches the rounded part of the LM35 sensor. If you accidentally connect the sensor the other way, it can be permanently damaged and you might need to replace it with another one. During the readings of the sensor, make sure that no other device uses the selected analog line, because it may interfere with the readings.
**Flash memory** is a non-volatile storage chip that can be electrically erased and reprogrammed. It was developed from EEPROM (electrically erasable programmable read-only memory) and must be erased in fairly large blocks before these can be rewritten with new data. The high density NAND type must also be programmed and read in (smaller) blocks, or pages, while the NOR type allows a single machine word (byte) to be written or read independently. Flash memories come in different sizes and supporting different clock speeds. They are mostly used for mass storage, as in USB Flash Drives, which are very popular today.

EasyPIC Fusion™ v7 features M25P80 serial Serial Flash Memory which uses **SPI communication interface** and has **8 Mbits** of available memory, organized as 16 sectors, each containing 256 pages. Each page is 256 bytes wide. Thus, the whole memory can be viewed as consisting of 4096 pages, or 1,048,576 bytes. Maximum clock frequency for READ instructions is 40MHz.

### What is SPI?

The **Serial Peripheral Interface Bus** or SPI bus is a synchronous serial data link standard that operates in full duplex mode. It consists of four lines **MISO** (Master Input Slave Output), **MOSI** (Master Output Slave Input), **SCK** (Clock) and **CS** (Chip Select). Devices communicate in master/slave mode where the master device initiates the data frame. Multiple slave devices are allowed with individual slave select (chip select) lines.

![Figure 22-1: Schematic of Serial Flash Memory module](image-url)

In order to connect Serial Flash Memory to the microcontroller you must enable **SW13.1**, **SW13.2**, **SW13.3** and **SW13.4** switches. This connects SPI lines to **SCK**, **MISO**, **MOSI** and **RD14** (CS) microcontroller pins.
EEPROM is short for Electrically Erasable Programmable Read Only Memory. It is usually a secondary storage memory in devices containing data that is retained even if the device loses power supply. EEPROMs come with parallel or serial interface to the master device. Because of the ability to alter single bytes of data, EEPROM devices are used to store personal preference and configuration data in a wide spectrum of consumer, automotive, telecommunication, medical, industrial, and PC applications.

EasyPIC Fusion™ v7 supports serial EEPROM which uses I²C communication interface and has 1024 bytes of available memory. EEPROM itself supports single byte or 16-byte (page) write and read operations. Data rates are dependent of power supply voltage, and go up to 400 kHz for 3.3V power supply.

What is I²C?

I²C is a multi-master serial single-ended bus that is used to attach low-speed peripherals to computer or embedded systems. I²C uses only two open-drain lines, Serial Data Line (SDA) and Serial Clock (SCL), pulled up with resistors. SCL line is driven by a master, while SDA is used as bidirectional line either by master or slave device. Up to 112 slave devices can be connected to the same bus. Each slave must have a unique address.
Digital signals have two discrete states, which are decoded as high and low, and interpreted as logic 1 and logic 0. Analog signals, on the other hand, are continuous, and can have any value within defined range. A/D converters are specialized circuits which can convert analog signals (voltages) into a digital representation, usually in form of an integer number. The value of this number is linearly dependent on the input voltage value. Most microcontrollers nowadays internally have A/D converters connected to one or more input pins. Some of the most important parameters of A/D converters are conversion time and resolution. Conversion time determines how fast can an analog voltage be represented in form of a digital number. This is an important parameter if you need fast data acquisition. The other parameter is resolution. Resolution represents the number of discrete steps that supported voltage range can be divided into. It determines the sensitivity of the A/D converter. Resolution is represented in maximum number of bits that resulting number occupies. Most microcontrollers have 10-bit resolution, meaning that maximum value of conversion can be represented with 10 bits, which converted to integer is $2^{10}=1024$. This means that supported voltage range, for example from 0-3.3V, can be divided into 1024 discrete steps of about 3.222mV.

EasyPIC Fusion™ v7 provides an interface in form of potentiometer for simulating analog input voltages that can be routed to any of the 5 supported analog input pins.

In order to connect the output of the potentiometer P1 to RB0, RB1, RB4, RB8 or RB9 analog microcontroller inputs, you have to place the jumper J8 in the desired position. By moving the potentiometer knob, you can create voltages in range from GND to VCC.

Figure 24-1: Schematic of ADC input
Additional GNDs

EasyPIC Fusion™ v7 contains GND pins located in different sections of the board, which allow you to easily connect oscilloscope GND reference when you monitor signals on microcontroller pins, or signals of on-board modules.

1. GND is located just below power supply section.
2. GND is located below the micro SD section.
3. GND is located just above PORTG/L Input/Output Group.

Figure 25-1: three oscilloscope GND pins are conveniently positioned so different parts of the board can be reached with an oscilloscope probe.
What’s Next?

You have now completed the journey through each and every feature of EasyPIC Fusion™ v7 board. You got to know it's modules, organization, supported microcontrollers, programmer and debugger. Now you are ready to start using your new board. We are suggesting several steps which are probably the best way to begin. We invite you to join thousands of users of EasyPIC™ brand. You will find very useful projects and tutorials and can get help from a large ecosystem of users. Welcome!

1. Compiler

You still don’t have an appropriate compiler? Locate dsPIC®/PIC24® or PIC32® compiler that suits you best on our website:

Choose between mikroC®, mikroBasic® and mikroPascal®, and download fully functional demo version, so you can begin building your dsPIC®/PIC24® and PIC32® applications.

2. Projects

Once you have chosen your compiler, and since you already got the board, you are ready to start writing your first projects. We have equipped our compilers with dozens of examples that demonstrate the use of each and every feature of the EasyPIC Fusion™ v7 board, and all of our accessory boards as well. This makes an excellent starting point for your future projects. Just load the example, read well commented code, and see how it works on hardware. Browse through the compiler Examples on this link:

3. Community

If you want to find answers to your questions on many interesting topics we invite you to visit our forum at http://www.mikroe.com/forum and browse through more than 150 thousand posts. You are likely to find just the right information for you. On the other hand, if you want to download free projects and libraries, or share your own code, please visit the Libstock™ website. With user profiles, you can get to know other programmers, and subscribe to receive notifications on their code.

4. Support

We all know how important it is that we can rely on someone in moments when we are stuck with our projects, facing a deadline, or when we just want to ask a simple, basic question, that's pulling us back for a while. We do understand how important this is to people and therefore our Support Department is one of the pillars upon which our company is based. MikroElektronika offers Free Tech Support to the end of product lifetime, so if something goes wrong, we are ready and willing to help!
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